

Geometric shape fitting based on Optimal Transport using Lipschitz Networks

 $\mathsf{Minimize} \ \theta \to \theta - \nabla_{\theta} \mathsf{EMD}_{\phi} \quad \blacktriangleleft$

Parametrized shape: θ

This is a parametrization of an arbitrary geometric shape, for instance, the radius and coordinates of the center of a circle. Many novel (and old) observables can be constructed as such. N-subjet \rightarrow N-points Pile-up \rightarrow Uniform rectangle N-circliness, N-diskiness, Triangularness, etc.



EMD Estimation

Using the KR duality, a lower bound on the $\text{EMD}_{\phi}(\mathbb{P}_{\theta}, \mathbb{Q})$ is estimated by the NN which is then minimized by the shape parameters in the following minimax optimization problem:



 $O(\mathbb{Q}) = \min_{\theta} \max_{\phi} \left[\sum_{i=1}^{n} E^{i} f_{\phi}(\mathbf{x}^{i}) - \sum_{i=1}^{m} w_{\theta}^{i} f_{\phi}(\mathbf{y}_{\theta}^{i}) \right]$ $O(\mathbb{Q}) \text{ is the observable that describes how well the event } \mathbb{Q} \text{ is described by the class of geometric objects } \mathbb{P}.$

Maximiz

Parametrized Distribution

This is a collection of *m* particles parametrized by θ : $\mathbb{P} = \{w_{\theta}^{i}, \mathbf{y}_{\theta}^{i}\}_{i=1}^{m}$ Examples: drawn from $\mathcal{N}(\mu, \sigma)$, uniform circles, disks, triangles, uniform rectangles, etc.

Target Distribution





Lipschitz NN

Each particle is passed individually to a Lipschitz 1 neural network $f_{\phi}(\mathbf{x})$ with parameters ϕ . Linear layers are weight normed such that

 $\|W^{(1)}\|_{p,\infty} \prod_{l=2} \|W^{(l)}\|_{\infty} \leq 1$ To approximate the EMD well, the NN architecture needs to be a universal approximator of Lip 1 functions. So we use GroupSort activation.

The event to fit given by a collection of particles: $\mathbb{Q} = \{E^i, \mathbf{x}^i\}_{i=1}^n$

Backward passForward pass







The NSF Institute for Artificial Intelligence and Fundamental Interactions